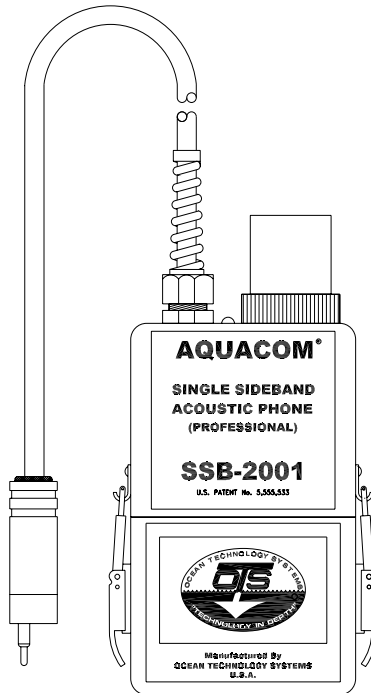


Aquacom[®]



SSB-2001 B-2

**2-Channel, Single-Sideband
Acoustic Transceiver**



“Technology in Depth”

- NOTICE -

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- IMPORTANT SAFETY NOTICE -
(Please read before using product.)

It is absolutely essential that all divers are properly trained and equipped and fully understand this user's manual before attempting to use the Aquacom® SSB-2001B-2.

While the SSB-2001B-2 provides divers with good underwater communications, it does not change or eliminate the potential hazards of diving!

Refer to the Library page of our Web site, www.otscmm.com, for a list of any changes made to this manual since its publication.

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SECTION 1

INTRODUCTION

1.1 GENERAL

Congratulations! You have just purchased one of the finest, state-of-the-art underwater communication systems available. The Aquacom[®] SSB-2001B-2 is an ultrasonic, single-sideband transceiver designed to allow through-water voice communications among divers and the surface. It employs *digital signal processing* (DSP) techniques that ensure the highest-quality intelligibility possible. Standard features include automatic electronic switching between voice activation (VOX) and push-to-talk (PTT) modes, allowing the diver total function control underwater; separate volume controls for receive and side audio levels; two channels; a heavy-duty housing; convertibility to a portable surface station; and more! In all, you will find that the functionality and versatility of the SSB-2001B-2 will greatly enhance your diving experience.

This user's manual contains information regarding the Aquacom[®] SSB-2001B-2 underwater communication system, including earphone-microphone assemblies and support equipment.

The SSB-2001B-2 with optional EMA-2 earphone-microphone assembly is illustrated in Figure 1.

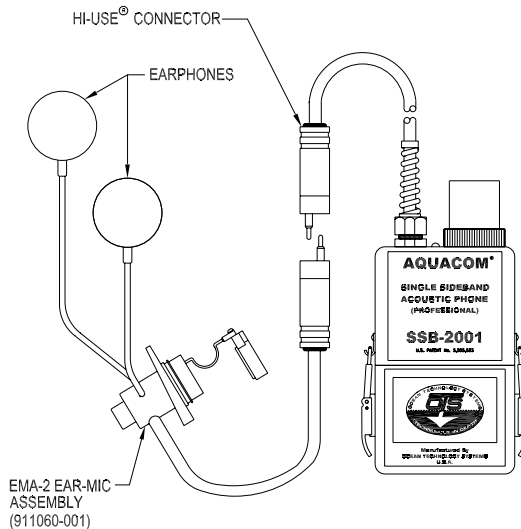


Figure 1. SSB-2001B-2 with typical earphone-microphone assembly

1.2 SPECIFICATIONS

Nominal range:	<i>Calm sea:</i> Greater than 1000 meters nominal <i>Sea State 6:</i> 200 meters nominal
Acoustic output power:	5 watts PEP ¹ (178.5 dB re 1 uPA at 1 meter)
Audio frequency response:	300–4000 Hz
Receiver sensitivity:	–110 dBv
Automatic gain control:	120 dB dynamic range
Transmitter activation:	Voice-operated transmitter (VOX) or manual activation (PTT)
Standard frequencies ² :	32.768 kHz USB (Channel 1) 25 kHz USB (Channel 7) ³
Battery life:	<i>Eight AA alkaline batteries:</i> 12 hours, assuming 10% transmission cycle. <i>RB-11 nickel-metal hydride battery pack (optional):</i> 6 hours.
Battery type:	Eight AA alkaline cells or optional RB-11 nickel-metal hydride rechargeable battery pack
Transducer:	Piezoelectric type
Earphone:	Ceramic type
Housing:	Injection-molded, high-impact, glass-filled ABS plastic
Maximum depth:	400 ft.
Housing dimensions:	Height 7.60”, width 3.55”, depth 1.80”
Operating temperature:	0°C to +60°C (+32°F to +140°F)
Storage temperature:	–10°C to +60°C (–14°F to +140°F)
Low-battery indication:	Red flashing LED on housing and beep in earphone
Connector type:	Hi-Use [®]
Battery chargers:	<i>RCS-15 and RCS-16:</i> 90–264 VAC, 50–60 Hz input; 14.7 VDC output; charging current 800 mA <i>RCL-7A:</i> 90–264 VAC, 50–60 Hz input; 24 VDC (diver units) and 16 VDC (surface units) output

1. PEP = “peak envelope power.”

2. These standard frequencies are also used by the STX-101M and the SSB-1001B.

3. 32.768 kHz USB is the more efficient channel with the supplied TA-5 transducer, but 25 kHz USB is more efficient if the optional TA-4 transducer is used (see Section 2.4.1).

1.3 WHEN YOU RECEIVE YOUR SHIPMENT

Upon arrival of your equipment, inspect the shipping container for dents, gouges, or any other evidence of rough handling.

When you remove your Aquacom® SSB-2001B-2 transceiver from the shipping container and the protective case, visually inspect it for damage or other problems. If any damage is evident, immediately file a claim with the carrier. Forward a copy of the damage claim to Ocean Technology Systems, Santa Ana, CA. We will then make arrangements for repair or replacement.

Also inspect the contents of the protective case to verify that all items have been included. See Section 2.1 for a list of items supplied with the SSB-2001B-2.

Note: Although the Aquacom® SSB-2001B-2 is rugged in design, exercise care to ensure that problems are not caused by improper handling. Store the unit in a safe, secure area after unpacking it.

SECTION 2

EQUIPMENT DESCRIPTION

2.1 GENERAL DESCRIPTION

The following items are provided with the Aquacom® SSB-2001B-2:

- SP-8 battery holder (for eight AA alkaline batteries) (p/n H024)
- AD-1 steel-tipped adjustment tool (p/n P088)
- User's manual (doc. no. 506087-000)
- Warranty card with the transceiver's serial number
- Large label of OTS logo (p/n 504013-002)
- OTS designed gear bag (for storage and transport), nylon, with shoulder strap (p/n 134153-000)

The SSB-2001B-2 is housed in a watertight enclosure constructed of high-impact, glass-reinforced ABS plastic that will not corrode if scratched and is designed for easy belt or tank mounting. The housing is divided into two major parts: the upper electronics and lower battery sections. An o-ring between the sections serves to maintain the housing's watertight integrity. Stainless steel latches maintain a constant pressure that preloads the o-ring and prevents leakage within specified depths. *(Note: The upper and lower housings are a matched set; do not mix them up with those of other transceivers.)*

The cable with a Hi-Use® connector allows the use of various standard or custom earphone-microphone (EM) assemblies designed for an assortment of diving masks and rebreathers and with microphones for a variety of underwater applications. Either alkaline or rechargeable batteries can be used. Overall, the SSB-2001B-2 was designed with simplicity and flexibility in mind.

For surface operation (diver-to-surface or vice versa), the user has the option to purchase the CDK-6 Surface Accessory Kit to transform the SSB-2001B-2 into a portable surface unit. Also available are the Aquacom® STX-101, STX-101M, SP-100D, and Magnacom® MAG-1001S surface stations. (Contact Ocean Technology Systems or your local OTS dealer for more information.)

2.2 FEATURES

The Aquacom® SSB-2001B-2 is equipped with **two channels**, 32.768 kHz upper sideband (USB) (Channel 1) and 25 kHz USB (Channel 7). It is designed for through-water, wireless communication with other transceivers operating at the same frequency.

Power is supplied by eight AA alkaline batteries (not included) or the RB-11 nickel-metal hydride (NiMH) rechargeable battery pack (p/n 900284-000, available from Ocean Technology Systems or your local OTS dealer).

Both **voice activation (VOX)** and **push-to-talk (PTT)** modes are available for transmission, and switching between them is done electronically for convenience. Separate **volume controls** are provided for receive and side audio, so that the diver can adjust the relative volume levels to his preference.

A **squelch** feature is included to provide quieter communications. The squelch, which functions similarly to the squelch of a CB radio, helps suppress background noises created by sea creatures, human activity, or other sources (e.g., snapping shrimp, croakers, motor boats, pool pumps). Below the squelch level set by the user, the squelch feature prevents any sound (presumably just noise) from being heard through the earphones. Louder sound (e.g., received communications) will “break” the squelch, allowing the received sounds to be heard. When the squelch is used, you will hear only the communication signals strong enough to break the squelch, so communication range is limited. If long communication range is desired, minimal or no squelch should be used. If the diver is working close-range to other divers or a surface station, an increased setting can be used. The optimal squelch sensitivity setting for your diving conditions is one that is high enough to screen out as much ambient noise as possible while still allowing all communications from your group to be heard.

2.3 FUNCTIONS AND CONTROLS

This section describes the various functions and controls of the Aquacom® SSB-2001B-2. For detailed instructions for how to make adjustments and operate the unit, see Section 3.

Refer to Figures 2 and 3 for the locations of the items referred to in this section. To access the controls depicted in Figure 3, follow the instructions in Section 3.1.1 to separate the upper and lower housings and to reseal them afterward.

The SSB-2001B-2 provides a switch for channel selection in addition to manual adjustment controls for receiver and side audio listening volumes and squelch and VOX sensitivities (Fig. 3). Because the unit is opened to access these controls, adjustments must be made on the surface, not while diving. An AD-1 steel-tipped adjustment tool is provided with the SSB-2001B-2. Switching between voice-activation (VOX) and push-to-talk (PTT) transmission modes is done electronically with PTT button push sequences and thus can be done while diving.

2.3.1 MANUAL PUSH-TO-TALK (PTT) SWITCH: The PTT button on the earphone-microphone (EM) assembly (sold separately) is used to enter transmission mode manually and to toggle between voice activation (VOX) and manual PTT transmission modes. Because there are many different configurations of diving masks, the location of the PTT button varies among EM assemblies. See Sections 3.1.2.1 (VOX/PTT Mode Selection) and 3.5 (Transmission) for instructions for use of the PTT and Section 2.4.2 for information about available earphone-microphone assemblies.

Key

- (1) Hi-Use® connector for EM assembly
- (2) Strike
- (3) Belt clip
- (4) O-ring to seal housing
- (5) Latch
- (6) Lower housing
- (7) SP-8 battery holder
- (8) Battery snap connector
- (9) Upper housing
- (10) Gripper ring
- (11) O-ring to seal transducer connection
- (12) Transducer
- (13) Activating water-contact screws
- (14) Power/charging indicator LED

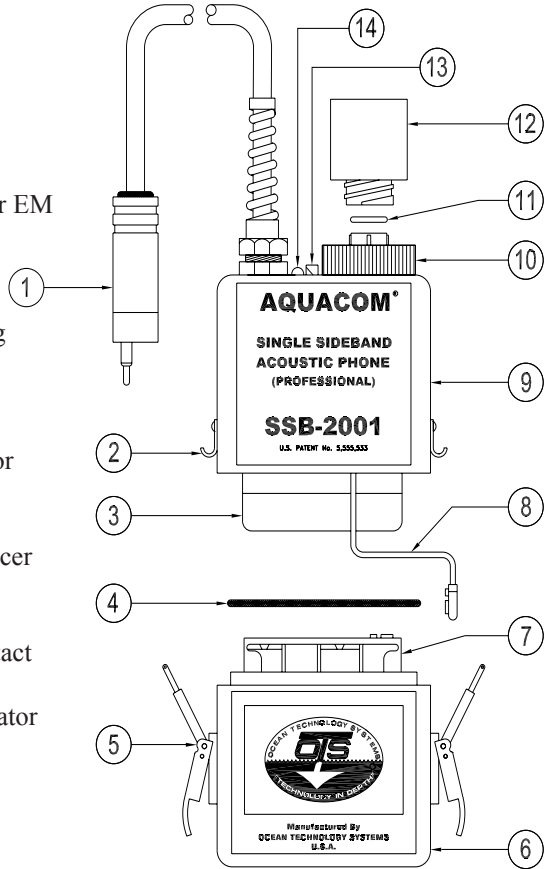
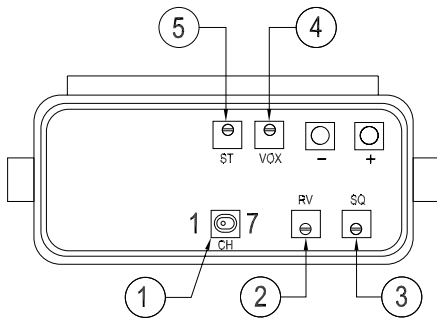


Figure 2. Components of the SSB-2001B-2



Key

- (1) Channel selection switch
- (2) Receive volume control
- (3) Squelch sensitivity control
- (4) VOX sensitivity control
- (5) Side audio volume control

Figure 3. Adjustment controls

2.3.2 VOICE-OPERATED TRANSMITTER (VOX): VOX operation provides hands-free communications. When the SSB-2001B-2 is in VOX transmission mode, simply talk for the unit to transmit automatically. The diver can adjust the VOX sensitivity with a control (Fig. 3, #4) to customize the VOX response to his voice and the level of ambient noise. It is a two-turn control, meaning it will rotate in either direction a total of two times before it stops. Section 3.1.2.1 provides instructions for switching between VOX and PTT modes, and Section 3.1.2.4 describes how to adjust the VOX sensitivity.

2.3.3 CHANNELS/FREQUENCIES: The SSB-2001B-2 provides two channels for transmission and reception: 32.768 kHz USB (Channel 1) and 25 kHz USB (Channel 7). 32.768 kHz USB is the more efficient channel with the supplied TA-5 transducer (Fig. 2, #12), but 25 kHz USB is more efficient if the optional TA-4 transducer is used instead. See Section 3.1.2.2 for channel selection instructions.

2.3.4 RECEIVE VOLUME: A manual control (Fig. 3, #2) is used to adjust the listening volume of communication signals received from other transmitters. Rotation clockwise increases the volume and counterclockwise decreases it. It is a two-turn control, rotating in either direction a total of two times before it stops.

2.3.5 SIDE AUDIO VOLUME: *Side audio* (also known as “sidetone”) is the diver’s transmitted signal heard through his own earphones. Side audio is useful for the diver to verify he is actually transmitting. Volume is changed by rotation of the side audio volume control (Fig. 3, #5), clockwise to increase and counterclockwise to decrease. It is a two-turn control, fully rotating twice before stopping.

2.3.6 SQUELCH: As explained in Section 2.2, the squelch helps to limit the background noise heard by the diver. The proper setting depends on the specific requirements of the dive. Squelch adjustment is accomplished via a manual control (Fig. 3, #3) and is described in Section 3.1.2.5. It is a two-turn control, meaning it will rotate in either direction a total of two times before it stops.

2.4 COMPONENTS AND ACCESSORIES

2.4.1 TRANSDUCER: The transducer provides the “antenna” for the transceiver to transmit and receive messages. It is mounted on the top of the upper housing (Fig. 2, #12) and is removable via a connector. A large gripper ring (Fig. 2, #10) provides a means to remove and reinstall the transducer easily, by holding the ring for stability while unscrewing the transducer.

Installed onto the standard Aquacom® SSB-2001B-2 is a TA-5 transducer, which operates more efficiently and therefore provides greater output power at Channel 1 (32.768 kHz USB) than at Channel 7 (25 kHz USB). If you require greater output power with Channel 7 (25 kHz USB) than with Channel 1, obtain an SSB-2001B-2 with a TA-4 transducer, available as a special order from Ocean Technology Systems or through your local OTS dealer.

An o-ring is located inside the transducer connector (Fig. 2, #11) to maintain a watertight seal. When reinstalling the transducer after having removed it from the upper housing, be sure to replace the o-ring to protect the connector pins from water entry and subsequent corrosion.

2.4.2 EARPHONE-MICROPHONE (EM) ASSEMBLIES: We offer our standard microphones integrated into EM assemblies designed to fit the communication port of full-face masks (FFMs) produced by various manufacturers. Table 1 is a compatibility chart of some of the standard EM assemblies available for use with Aquacom® diver transceivers. *Note: If you have a diving helmet or FFM that is not on the compatibility chart, contact Ocean Technology Systems or your local OTS dealer for availability or for information on custom EM assemblies.*

The following are full descriptions of each of the EM assemblies listed in Table 1:

2.4.2.1 EMA-2 (911060-001): The EMA-2 EM assembly is designed for all Divator MKII (“AGA”) full-face masks (FFMs). It has two ceramic earphones with holders, an ME-16R Hot-Mic®, a Hi-Use® connector, and a push-to-talk (PTT) button. The assembly is installed into the Divator MKII FFM communication port.

2.4.2.2 EMA-2SM (911060-098): The EMA-2SM EM assembly is designed to be installed into all Divator MKII (“AGA”) FFMs. It consists of two ceramic earphones with holders, a Super Mic, a Hi-Use® connector, and a PTT button. The assembly is installed into the Divator MKII FFM communication port.

2.4.2.3 EMX-2 (911060-008): The EMX-2 EM assembly is designed for the EXO-26 *original* FFM. It consists of two dynamic earphones, an ME-16R Hot-Mic, a Hi-Use® connector, and a PTT button.

2.4.2.4 EMX-2B (911060-026): The EMX-2B EM assembly is designed for the EXO-26 *standard* full-face mask. It is similar to the EMX-2 but fits the balanced-regulator version of the EXO-26 with an oral-nasal cavity.

2.4.2.5 EMO-2 (900096-686): The EMO-2 EM assembly is designed to be installed into the Ocean Reef NIRA Neptune FFM. It has two earphones with holders, a Hot-Mic, a Hi-Use® connector, and a PTT button. It is installed into a port on the side of the FFM.

2.4.2.6 EMH2-1 (911060-009): The EMH2-1 EM assembly is optionally included with the HM-2 mouth mask. It has one head strap, one ceramic earphone, a Hot-Mic, a Hi-Use® connector, and a PTT button (located on the HM-2 mask).

2.4.2.7 EMH2-1SM (911060-100): The EMH2-1SM EM assembly is optionally included with the HM-2 mouth mask. It has a head strap, one ceramic earphone, a Super Mic, a Hi-Use® connector, and a PTT button (on the HM-2 mask).

2.4.2.8 EMS-2 (911060-017): The EMS-2 is an EM assembly designed to be

Table 1. Compatible Earphone-Microphone Assemblies

<i>Model Number</i>	<i>Part Number</i>	<i>Type</i>	<i>Microphone</i>	<i>Earphones</i>	<i>Mask/Rebreather</i>
EMA-2	911060-001	Standard ear-mic	Hot-Mic®	Dual	Divator MK II FFM
EMA-2SM	911060-098	Standard ear-mic	Super Mic®	Dual	Divator MK II FFM
EMA-SW-1	910274-000	SW ear-mic	Hot-Mic	Dual	Divator MK II FFM
EMA-SW-1SM	910274-001	SW ear-mic	Super Mic	Dual	Divator MK II FFM
EMA-MK24	910279-000	SW ear-mic	Hot-Mic	Dual	MK-24 FFM
EMA-MK24-SM	910279-001	SW ear-mic	Super Mic	Dual	MK-24 FFM
EMDG-2	911060-076	Standard ear-mic	ME-500	Dual	Dräger Panorama Nova
EMX-2	911060-008	Standard ear-mic	Hot-Mic	Dual	EXO-26 original
EMX-2B	911060-026	Standard ear-mic	Hot-Mic	Dual	EXO-26 standard
EMH-MAG2	900332-000	Standard ear-mic	Hot-Mic	Single	HM-1 mouth mask
EMH-MAG2SM	900332-001	Standard ear-mic	Super Mic	Single	HM-1 mouth mask
HM-1SW	910281-000	SW ear-mic	MIL-500B	Single	HM-1 mouth mask
HM-1SW-SM	910281-001	SW ear-mic	Super Mic	Single	HM-1 mouth mask
EMH-1	911060-009	Standard ear-mic	Hot-Mic	Single	HM-2 mouth mask
EMH-1SM	911060-100	Standard ear-mic	Super Mic	Single	HM-2 mouth mask
LAR V Adapter	900282-000	Standard ear-mic	ME-500	Single	LAR V rebreather
LAR5-SW	900282-006	SW ear-mic	Dynamic mic	Dua	LAR V rebreather
EMD-2	911060-067	Standard ear-mic	Hot-Mic	Dual	M-48 SuperMask®
EMD-2SM	911060-101	Standard ear-mic	Super Mic	Dual	M-48 SuperMask®
EM-KMS-48	910280-000	SW ear-mic	Hot-Mic	Dual	M-48 SuperMask®
EM-KMS-48SM	910280-002	SW ear-mic	Super Mic	Dual	M-48 SuperMask®
EMMT-1	911060-090	Standard ear-mic	Hot-Mic	Single	Mantis FFM
EMMT-1SM	911060-102	Standard ear-mic	Super Mic	Single	Mantis FFM
EMMT-2	911060-091	Standard ear-mic	Hot-Mic	Dual	Mantis FFM
EMMT-2SM	911060-103	Standard ear-mic	Super Mic	Dual	Mantis FFM
EMO-2	900096-686	Standard ear-mic	Hot-Mic	Dual	Ocean Reef FFM
EMS-2	911060-017	Standard ear-mic	Hot-Mic	Dual	ScubaPro FFM
EM-OTS-2	910369-000	Standard ear-mic	Hot Mic	Dual	Guardian FFM
EM-OTS-2SM	910379-000	Standard ear-mic	Super Mic	Dual	Guardian FFM

installed into a ScubaPro FFM. It consists of two earphones with holders, a Hot-Mic, a PTT button, and a Hi-Use® connector.

2.4.2.9 LAR V Adapter (900282-000): This adapter is placed between the inhalation hose and LAR V bite-mouth/DSV t-bit assembly. It is designed to allow basic words to be transmitted without the need for a full or half mask. It consists of one earphone, an ME-500 microphone, a Hi-Use® connector, and a PTT button.

2.4.2.10 EMD-2 (911060-067): The EMD-2 EM assembly is designed to be installed into the M-48 SuperMask® FFM. It consists of two earphones, earphone holders, a Hot-Mic, a Hi-Use® connector, and a PTT button.

2.4.2.11 EMD-2SM (911060-101): The EMD-2SM EM assembly is designed to be installed into the M-48 SuperMask® FFM. It consists of two earphone/earphone holders, a Super Mic, a Hi-Use® connector, and a PTT button.

2.4.2.12 EMDG-2 (911060-076): This assembly is designed to be installed into the Dräger Panorama Nova Dive Mask. It consists of two earphones, earphone holders, an ME-500 microphone, a Hi-Use® connector, and a PTT button.

2.4.2.13 EMH1-1 (900332-000): This assembly is designed to be installed into the HM-1 silicone half mask. It consists of one earphone, a Hot-Mic, a Hi-Use® connector, and a PTT button.

2.4.2.14 EMH1-1SM (900332-001): The EMH1-1SM EM assembly is designed to be installed into the HM-1 silicone half mask. It consists of one earphone, a Super Mic, a Hi-Use® connector, and a PTT button.

2.4.2.15 EMMT-1 (911060-090): The EMMT-1 EM assembly is designed to be installed into the Mantis FFM. It consists of one earphone, an earphone holder, a Hot-Mic, a Hi-Use® connector, and a PTT button.

2.4.2.16 EMMT-1SM (911060-102): The EMMT-1SM EM assembly is designed to be installed into the Mantis FFM. It consists of one earphone/earphone holder, a Super Mic, a Hi-Use® connector, and a PTT button.

2.4.2.17 EMMT-2 (911060-091): This assembly is designed to be installed into the Mantis FFM. It consists of two earphones, two earphone holders, a Hot-Mic, a Hi-Use® connector, and a PTT button.

2.4.2.18 EMMT-2SM (911060-103): This assembly is designed to be installed into the Mantis FFM. It consists of two earphone/earphone holders, a Super Mic, a Hi-Use® connector, and a PTT button.

2.4.2.19 EM-OTS-2 (910369-000): This assembly is designed to be installed into the Guardian FFM. It consists of two earphone/earphone holders, a Hot-Mic, a Hi-Use® connector, and a PTT button.

2.4.2.20 EM-OTS-2SM (910379-000): This assembly is designed to be installed into the Guardian FFM. It consists of two earphone/earphone holders, a Super Mic, a Hi-Use® connector, and a PTT button.

2.4.3 MICROPHONES:

2.4.3.1 ME-16R Hot-Mic® (912086-000): The ME-16R Hot-Mic® is a 150-ohm, water-resistant microphone element. It is a state-of-the art dynamic microphone element designed to give you long, trouble-free use and the highest intelligibility possible.

Although the Hot-Mic is trouble free, it should be maintained. Rinse it with

freshwater after use to get all dirt, debris, or salt water from the grill. Dry it with a clean, soft towel. If the element ever needs to be replaced, it is easily removed by unscrewing the two small screws located on its base.

Getting the microphone wet does not harm it. However, the microphone element can only withstand an 8- to 10-foot depth/pressure differential. If you removed your diving FFM at the back of the boat and the microphone became wet, there would be no problem; but if the FFM with element dropped more than 8 to 10 feet into the water, the change in pressure probably would damage the microphone element. In tests we have taken off the FFM at 30 feet and replaced it, still at 30 feet, without any problem; but if one were to take off the FFM at 30 feet and drop down to 40 feet, the pressure difference may damage the microphone.

2.4.3.2 Super Mic® Depth Master: The Super Mic offers patented technology* that overcomes a limitation of other microphones. It can be used at any depth and—unlike the Hot-Mic or many other microphones—can withstand changes in depth while submerged, so it will not be damaged if the diver needs to descend with the mask flooded (e.g., on removal and stowage of the full-face mask when switching to another air system). It is a ceramic microphone with a compact, lightweight design and noise-cancelling properties, reducing background noises for clearer communications. When only the highest quality of intelligibility is required, the Hot-Mic is the preferred choice; but the Super Mic's intelligibility is sufficient for most diving situations.

To assure clear communications when using the Super Mic, it should be no more than 1/4 inch from the corner of the diver's mouth.

After each dive, clean the Super Mic by rinsing it with freshwater and drying it with a clean, soft towel. No other maintenance is required.

Note: Do not press on the microphone diaphragm; doing so may cause damage.

2.5 COMPATIBLE SURFACE/DIVER TRANSCEIVERS

The SSB-2001B-2 transmits to and receives from any transceiver that is within range and set to the same frequency. The following are compatible transceivers manufactured by OTS:

Diver units: SSB-2010, SSB-1001B, Buddy Phone (e.g., XT-100, OTS-BUD, MKII-BUD, MTS-BUD, SCU-BUD, DSI-BUD, RX-100), MAG-1003D, MAG-1004HS

Surface units: STX-101, STX-101M, STX-101SB (25-kHz version), SP-100, SP-100D, MAG-1001S (a version with at least one compatible frequency must be requested), MAG-1003-PS

Diving bell unit: BELL-200

*U.S. Patent no. 7,170,822; EU patent nos. 000458351-0001, -0002, -0003, -0004, -0005, -0006.

SECTION 3

OPERATION INSTRUCTIONS

Here are provided instructions for operation of the Aquacom® SSB-2001B-2, including adjustments, setup before a dive, use during the dive, and what to do after the dive is over. Information on batteries, including charging instructions, is found in Section 4. Instructions for proper maintenance of the SSB-2001B-2 are in Section 5. With more information to help you understand how to set up and use your equipment for the best possible communications in your diving situation, Section 6 explains how communication is accomplished underwater and discusses the factors that affect it.

3.1 ADJUSTMENTS AND SETTINGS

The SSB-2001B-2 offers various settings to make best use of its features, including the capability to make manual adjustments to define the sensitivities of the VOX and squelch systems. Because no standards for design of full-face masks have been established, virtually all full-face masks have different internal designs. Some designs have little room for microphone installation, which makes it necessary to have a more sensitive setting. Overall, the ability to make these adjustments offers the user more options to customize the transceiver for optimal communications.

The following instructions explain how to make the adjustments and settings necessary for effective operation of the SSB-2001B-2. Refer to Section 2.3 (Functions and Controls) for the locations and descriptions of the controls.

3.1.1 ACCESSING THE INTERNAL CONTROLS: Most of the adjustments and settings described in this section require the upper and lower housings of the SSB-2001B-2 transceiver to be separated. To open the unit, do the following:

1. Place the transceiver so it stands on or against a stable surface.
2. Release the two latches (Fig. 2, #5) securing the upper and lower housings (#6 and #9).
3. Separate the two housings.

To rejoin the two housings and seal the unit, do the following:

1. Ensure the large o-ring (Fig. 2, #4) rests evenly and securely inside the groove along the bottom of the upper housing (#9).
2. Connect the battery snap connector (Fig. 2, #8) to the RB-11 battery or SP-8 battery holder (#7).
3. Being careful not to pinch the battery wire (Fig. 2, #8), join together the upper and lower housings such that their surfaces are completely flush.
4. Place the transceiver so it stands on or against a stable surface.

5. Raise the latches (Fig. 2, #5) on the lower housing over the catches (#2) on the upper housing. While taking care to maintain the seal between the two housings, pull both handles all the way down simultaneously until they snap to rest against the lower housing.
6. Check the unit to ensure the housings are tightly joined together with a watertight seal. (If water enters the unit, damage could result.)

3.1.2 MAKING ADJUSTMENTS AND SETTINGS

3.1.2.1 VOX/PTT Mode Selection: When the power is first turned on, the SSB-2001B-2 is in push-to-talk (PTT) transmission mode. To change to VOX mode, press the PTT button (Section 2.3.1) twice in one second. To change back to PTT mode, again press the PTT button twice in one second. Because the transmission mode is changed using the PTT button, this operation can be done underwater while diving. See Section 2.3.2 for more information on the VOX function and Section 3.1.2.3 for instructions for adjustment of VOX sensitivity.

3.1.2.2 Channel Selection: To choose between channels 1 and 7, separate the transceiver housings (Section 3.1.1) to access the control panel (to prevent water entry, this must be done on the surface, not while diving). Move the channel selection switch (Section 2.3.3) to the desired channel. While the unit is still open, you can make other adjustments if necessary (see Sections 3.1.2.3 through 3.1.2.5). When finished, rejoin and reseal the two housings as instructed in Section 3.1.1.

3.1.2.3 Audio Volume Adjustments: The receive and side audio volumes are adjusted independently. After separating the upper and lower housings (Section 3.1.1) to access the bottom of the upper housing, use the supplied AD-1 adjustment tool to rotate the two-turn volume controls (Sections 2.3.4 and 2.3.5). Rotate the controls clockwise to increase volume and counterclockwise to decrease it.

With some helmets or full-face masks, you may experience acoustic feedback while transmitting; in that case, a lower side audio volume setting must be used.

Because the housings must be separated to access the audio volume controls, these adjustments must be made on the surface, not underwater.

3.1.2.4 VOX Sensitivity Adjustment: The VOX sensitivity should be set for the diver's voice for optimal VOX response. If the VOX is not adjusted properly, either false transmission due to noise (if too sensitive) or an inability to transmit (if not sensitive enough) will occur.

To adjust the VOX sensitivity, use the supplied AD-1 adjustment tool to rotate the VOX control (Section 2.3.2) clockwise to increase VOX sensitivity or counterclockwise to decrease it. See Figure 4 for an illustration of the effect of adjustment on VOX sensitivity.

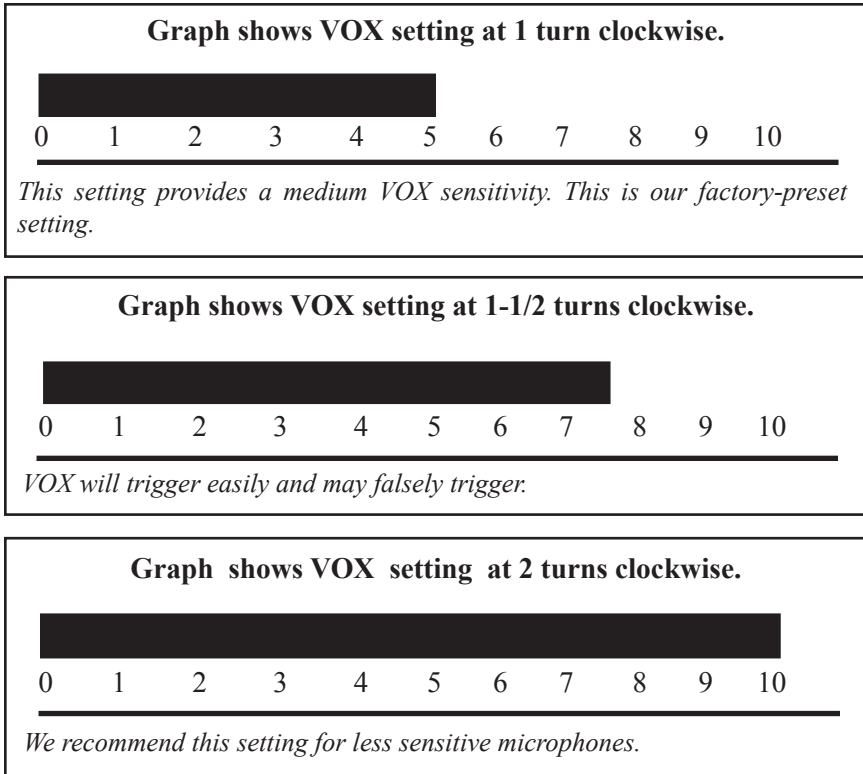


Figure 4. Effect of VOX sensitivity adjustment

Because the housings must be separated to access the VOX sensitivity control, this adjustment must be made on the surface, not underwater.

3.1.2.5 Squelch Sensitivity Adjustment: As explained in Section 2.2 (last paragraph), the squelch function helps to suppress background noises but also reduces range. To adjust its sensitivity level, open the unit (Section 3.1.1) and use the supplied AD-1 adjustment tool to turn up (clockwise) or down (counterclockwise) the squelch level. The effect of squelch adjustment is illustrated in Figure 5.

Because the housings must be separated to access the squelch sensitivity control, this adjustment must be made on the surface, not underwater.

3.2 SETUP BEFORE A DIVE

Preparing your SSB-2001B-2 for a dive involves installing proper batteries, inspection of the unit and accessories, a basic equipment check, preliminary electronic adjustments, and donning the unit with your dive gear. The following steps should be taken before each dive:

Graph shows squelch setting at 1 turn clockwise.



Use a relatively low setting for increased reception range.

Graph shows squelch setting at 1-1/2 turns clockwise.



Factory setting. Should work well for most operations.

Graph shows squelch setting at 2 turns clockwise.



Not recommended; may disable communications from divers and/or surface.

Figure 5. Effect of squelch sensitivity adjustment

1. If fresh alkaline or fully recharged batteries are not already in the transceiver, install them, or—if you are using the RB-11 nickel-metal hydride rechargeable battery pack (sold separately)—recharge the battery through the unit housing. See Section 4 for battery installation and recharging instructions.
2. Ensure both o-rings (Fig. 2, #4 and #11) are clean and in good condition. They should both be lightly lubricated with a quality, pure silicone grease. When reinstalling the transducer after inspecting its o-ring, ensure it is properly seated and secured.
3. Verify the battery connector wire (Fig. 2, #8) has not been pinched between the upper and lower housings of the transceiver. (A pinched wire would cause flooding, damaging the transceiver.)
4. Assure that the upper and lower housings are properly sealed together with no high spots.
5. Install the earphone microphone (EM) assembly into your full-face mask or helmet, according to the installation instructions provided with the EM as-

sembly. (See Section 2.4.2 for information on available EM assemblies.)

6. With a quality, pure silicone grease, lightly grease the two sockets and the plastic bases of the two pins of the Hi-Use[®] connectors of both the SSB-2001-B-2 (Fig. 2, #1) and the EM cable. Then fully join the two connectors.
7. Perform the following equipment check:
 - a. Locate the two activating water-contact screws (Fig. 2, #13) on top of the upper housing, between the transducer gripper ring and the red indicator LED. Moisten your fingers and place them across the screws to activate the unit (hold onto the screws for about 10 seconds). The unit will stay on for approximately 2 minutes out of water. The red LED will illuminate while power is on.
 - b. While the unit is still activated, test the unit by depressing the PTT button and talking into the mask microphone. You should hear your voice in the earphone(s) via side audio. Follow the procedure in Section 3.1.2.3 if the side audio volume needs to be adjusted.
 - c. If you are going to use the SSB-2001B-2 in the voice-activation (VOX) mode, set the unit to VOX mode (Section 3.1.2.1) and use a vowel sound such as “AH” or say the number “FOUR” to trigger the VOX. If the VOX is too sensitive or not sensitive enough, adjust it according to the instructions in Section 3.1.2.4.
 - d. Verify your transceiver is set to the same channel everyone else will be using, earphone volume levels (both receive and side audio) are to your liking, and the squelch sensitivity setting is proper for the underwater environment and required range (see Section 2.2). If the squelch setting needs to be adjusted, refer to Section 3.1.2.5 for instructions.
 - e. Repeat the above steps with another transceiver to verify that it is operational and on the same channel.
 - f. Using the AD-1 adjustment tool, turn the squelch sensitivity of both transceivers all the way down (counterclockwise). Place both units into a sink or pail of water (with enough water to completely cover the transducers), or place the transducers within four feet of each other out of water. Transmit back and forth between the transceivers to verify that both transmit and receive properly.

Note: The transceiver will not sound as clear during these tests as it will in open water.

8. Don your dive equipment, including the SSB-2001B-2, making sure that the cables are dressed out so as not to snag. Inspect your diver partner’s gear for the same.

You can use the following checklist as a final check before the dive.

Pre-Dive Checklist

1. Fresh alkaline batteries or a fully charged NiMH battery pack installed.
2. O-rings lightly greased and in place.
3. Clamps secure, no pinched wires.
4. Diver unit in place, transducer free of diving equipment.
5. Earphone(s) in holder(s) and adjusted.
6. Hi-Use® connectors properly mated and pins lightly greased.
7. Diver is dressed out such that the cables will not snag and the transducer is not covered by any type of dive equipment.
8. In-water surface check:
 - a. Recheck the location of the earphone.
 - b. Submerge the transducer and establish communication.
 - c. Look your dive partner over to ensure his equipment is properly adjusted and the wires are dressed so as not to snag.

Important Safety Notes

- (1) *Conduct a pool checkout and have more pool practice before using the system in open water. Aquacom® systems provide divers with good underwater communications but do not change or eliminate potential diving hazards.*
- (2) *Use any standard safe entry into the water, but be aware of the additional equipment you are wearing. The transceiver and cables should be positioned so they do not snag or hit against anything during entry. Keep a copy of the above checklist handy for reference before entering the water.*
- (3) *It is absolutely essential for all divers to be properly trained and equipped before responding to distress, emergency, and safety calls.*
- (4) *Never begin an ascent while holding your breath (air embolism may occur).*

3.3 POWER ACTIVATION

The power is activated by simultaneous contact of the two activating water-contact screws (Fig. 2, #13) with water, so the power will activate automatically when the transceiver is submerged. The red indicator LED (Fig. 2, #14) will illuminate when the transceiver power is on. The unit's power remains activated for approximately 2 minutes out of water.

3.4 RECEPTION

When the power is activated, the SSB-2001B-2 will automatically be in receive mode, so you will hear all communications within range and on the same channel.

For optimal reception, adjust the squelch sensitivity to the setting that best screens out background noises while still providing the reception range you require (see Sections 2.2 and 2.3.6 for more information about the squelch function and Section 3.1.2.5 for squelch adjustment instructions).

When receiving a transmission, do the following:

- Relax.
- Concentrate on hearing.
- Try different earphone positions until the best one is found.
- Minimize exhalation bubble noise, but do not hold your breath.

Most divers find that an inhalation cycle is the best time to receive a message. While off-gassing, the bubble noise makes hearing difficult.

If you experience acoustic feedback while transmitting, use a lower side audio volume setting (see Section 3.1.2.3).

3.5 TRANSMISSION

When the SSB-2001B-2 is in PTT transmission mode, simply depress the PTT button to transmit. The system automatically returns to the receive mode upon release of the PTT button. If the unit is in VOX transmission mode (see Section 2.3.2), pressing the PTT button to transmit overrides the VOX function.

To transmit in VOX mode, all you have to do is speak for the transceiver to enter transmission mode automatically. However, as explained in Section 3.1.2.4, the VOX sensitivity should be calibrated to the diver's voice to assure that the unit enters transmission mode whenever (and only when) the diver speaks.

As discussed in Section 3.1.2.1 (VOX/PTT Mode Selection), when the unit is first turned on, the SSB-2001B-2 is in PTT transmission mode. To change back and forth between VOX and PTT modes, press the PTT button twice in once second.

3.6 AFTER THE DIVE

1. Disconnect the Hi-Use[®] connector from the mask or helmet. Remove your mask or helmet. Remove your SSB-2001B-2 transceiver.
2. As soon as possible, rinse the unit in freshwater to remove salt and other mineral deposits.
3. Although the Aquacom[®] SSB-2001B-2 is ruggedly constructed for long life in the marine environment, we strongly recommend that you place it in a protective carrying case between dives, taking special care to avoid damaging the transducer.

3.7 HELPFUL HINTS

(Note: This list is not in order of priority.)

1. Your speech should be considerably slower than normal, and each word should be pronounced clearly and distinctly. Speak one word at a time instead of in flowing sentences. Do not shout, but use slightly louder than normal conversation volume. Minimize exhalation while speaking. Your communication will

be more easily understood if you are relaxed, since speech is less intelligible as a diver becomes more anxious.

2. Listen for a break in conversation if others are communicating on the same channel in the area. Identify whom you are calling and then identify yourself. Continue speaking until the message is complete. At the end of each message, say “Over” if a response is required and “Out” if not. (See Section 3.8.)
3. The microphone element should be within 1/4 inch of the diver’s lips, especially if the microphone has noise-cancelling properties. (See Section 2.4.3.)
4. Designate one diver as lead communication diver so that more than one diver will not be trying to answer questions.
5. Brief the divers that after entering the water, especially if making a jump, they should make eye contact with the dive supervisor (if he has a surface station) and establish communications.
6. If a diver feels a thermocline, he should report the depth to other divers and the dive supervisor (if he has a surface station). Topside should adjust the transducer accordingly.
7. Do initial underwater training in a controlled area (e.g., a swimming pool).
8. During initial training, if you have a surface transceiver, talk to one diver at a time until he establishes clear communications. Then talk to the other. After the divers are comfortable, have them talk to each other.
9. If working in a pool, make sure the pool does not have a bad or noisy pump. This would create many tiny bubbles that would reduce the communication range. If after a few minutes you see tiny bubbles (like carbonation) gathering on your hands or dive gear, move to a new location or fix the pump. If the pump is noisy, secure it during the test.
10. Surface units within range can communicate in open water or harbors, avoiding the sometimes crowded and less private airways. Submarine or bell crews can similarly communicate with one another or with surface units. We recommend the use of standard radio/telephone procedures in all communications.

3.8 EXAMPLES OF UNDERWATER COMMUNICATION

3.8.1 CALLS BETWEEN SURFACE, SUBS, OR DIVERS:

DIVER A: Red Diver, this is Blue Diver, do you see the wreck yet? Over.

DIVER B: Blue Diver, this is Red Diver, yes, I see the wreck, it’s ten yards to your right. Out.

3.8.2 CALLS BETWEEN DIVERS AND SURFACE, SUBS, OR BELLS:

DIVER A: Topside, this is Blue Diver, how far am I from the dive boats? Over.

SURFACE: Blue Diver, this is Topside, I see your bubbles 50 feet off my port bow. Out.

DIVER A: Sub, this is Blue Diver, how long before I must lock in? Over.

SUB: Blue Diver, this is Sub, we expect you in seven minutes. Out.

SECTION 4

BATTERIES AND CHARGING

The SSB-2001B-2 can be powered using eight standard AA-size alkaline batteries, for which we supply an SP-8 battery holder inside the battery compartment of the transceiver's lower housing. A nickel-metal hydride (NiMH) rechargeable battery pack (the RB-11) and chargers (see Table 2) are available as an option and can be purchased separately. We also offer a multi-battery charger (the RCL-7A) with the ability to charge multiple batteries simultaneously, as well as a surface unit's battery.

The RB-11 NiMH battery pack delivers greater capacity than nickel cadmium (NiCad) batteries and does not suffer from "memory effect" as do NiCad batteries.

Refer to Table 2 for a list of available battery chargers and their features. If you intend to purchase any extra RB-11 battery packs to replace the battery without having to wait for one to charge, then obtain the RCS-16 (smart charger with power cords available for any region of the world), which provides the option of charging the RB-11 battery pack either outside or inside the SSB-2001B-2 transceiver. As another alternative, the RCL-7A multi-battery charging station can charge up to six RB-11 batteries and a surface transceiver battery simultaneously. The RCS-15 charger can charge only a battery pack that is inside the transceiver and only one pack at a time.

Note: The RB-11 rechargeable battery you receive may have upgraded specifications from what is stated in this manual. Due to advancing battery technologies, we continually upgrade our batteries and chargers. Contact OTS or your OTS dealer to find out the latest available battery and charger.

Table 2: Battery Chargers Available for the SSB-2001B-2

Model No.	Part No.	Region	Specifications	Charging Method
RCS-15	910376-xxx	Any	90–264 VAC, 50–60 Hz input; 24 VDC output	Via transceiver
RCS-16	900289-001	Any	90–264 VAC, 50–60 Hz input; 24 VDC output	Via transceiver/ Battery directly
RCL-7A	900307-000	Any	90–264 VAC, 50–60 Hz input; 24 VDC (diver units) and 16 VDC (surface units) output	Battery directly

4.1 BATTERY INSTALLATION OR REPLACEMENT

One should never try to recharge alkaline batteries; they should be discarded and replaced when depleted. If you use an RB-11 NiMH rechargeable battery pack, after a long life of service it may no longer adequately hold a charge and may need to be replaced. Whether you need to install new or replace old batteries, follow these steps (refer to Figure 2 for the locations of the transceiver components):

1. Place the SSB-2001B-2 transceiver onto a stable surface.
2. Pull up on the latches (Fig. 2, #5) simultaneously.
3. Separate the upper and lower housings while being careful not to damage the wires or o-ring.
4.
 - a. *Alkaline batteries:* Load fresh alkaline AA batteries per the directions stated on the SP-8 battery holder.
 - b. *RB-11 rechargeable battery:* The RB-11 is used instead of the SP-8 battery holder, which must be removed from the lower housing. If you are replacing a currently installed battery, disconnect the battery connector. Remove the old battery from the lower housing. Install the charged battery by inserting it into the transceiver's lower housing and connecting the battery connector.
6. Verify that the o-ring (Fig. 2, #4) is in place, lightly lubricated with a quality pure silicone grease, and free of debris.
7. Carefully mate the upper and lower housings together. Ensure that they line up evenly and that nothing is on the o-ring or mating surface.
8. Connect the latches from the lower housing to the upper strikes (Fig. 2, #2). Pull down the latches simultaneously until fully down.
9. Look on all sides of the transceiver to verify the upper and lower assemblies appear flush with no high spots. *Note: If the housing is not completely sealed, water will enter during the dive and may damage the battery.*

4.2 BATTERY CHARGING

The RB-11 NiMH battery pack can be recharged using the chargers listed in Table 2. *Never attempt to recharge alkaline batteries.*

IMPORTANT NOTE: If RB-11 rechargeable batteries were supplied with your transceiver, recharge the batteries before first use.

Before operating the transceiver, allow a few minutes after charging the batteries for any gasses caused by charging to dissipate.

4.2.1 CHARGING THROUGH THE TRANSCEIVER: With an RCS-15 charger, or an RCS-16 charger with the battery snap adapter removed, it is not necessary to open the transceiver to charge the RB-11. Follow these simple instructions:

1. Remove and set aside the transducer (Section 2.10.1).

2. *RCS-15*: Follow the instructions provided with the RCS-15 charger. The RCS-15 monitors the battery's voltage level to charge it only as necessary.
3. Replace the transducer (ensure the o-ring is in place and in good order).

4.2.2 CHARGING THE BATTERY DIRECTLY

- *RCS-16 charger (with the supplied battery connection adapter)*:
Follow the instructions provided with the RCS-16 charger. The RCS-16 monitors the battery's voltage level to charge it only as necessary.
- *RCL-7A multi-battery charging station*:
Follow the operating instructions in the RCL-7A user's manual.

SECTION 5

MAINTENANCE

5.1 GENERAL MAINTENANCE

The SSB-2001B-2 is virtually maintenance free and should give you many years of service. Follow the instructions in Section 3.6 (After the Dive) for a general maintenance procedure after each use.

5.2 PERIODIC MAINTENANCE

Perform the following service periodically on the SSB-2001B-2:

1. Clean and lightly grease the orings in the transducer (Fig. 2, #11) and between the upper and lower housings (#4). Check the o-rings for cracks or damage. If there is any evidence, replace the o-ring. *Note: Do not grease the transducer!*
2. Keep the transducer clean. Periodically wipe it clean with alcohol (around the outside, not underneath or on the connector).
3. Verify that the screws securing the battery wire (Fig. 2, #8) are tight.
4. Verify that the battery connector and wire are undamaged, clean, and otherwise in good order.

SECTION 6

THE BASICS OF SOUND IN WATER

6.1 BACKGROUND

If a diaphragm submerged in water is caused to vibrate by electrical means, it has mechanical energy of motion that is communicated to the water. If another diaphragm is submerged in the water near the vibrating diaphragm, the acoustic energy in the water will excite mechanical vibrations in the second diaphragm. These vibrations may be detected by electrical means to complete a flow of mechanical energy from the first diaphragm to the second. The first diaphragm is called the *source* or *transducer*, and the second is called a *receiver* or *hydrophone*. In Aquacom® systems, the transducer and hydrophone are one and the same.

6.2 FACTORS THAT AFFECT SOUND IN WATER

There are many factors that affect the propagation of sound in water. All of these factors vary depending upon location, depth, and time of day. The net result is that communication in water can be affected by local conditions and the kind and depth of dive being conducted. Fluctuations in range and intelligibility are to be expected.

6.2.1 Distance: The sound intensity from a source varies inversely with the square of the distance from the source. This sort of variation is referred to as *spherical spreading*. Other factors also influence the variation of sound intensity with distance. As the sound passes through the water, some of the energy is absorbed and converted to heat (*attenuation*) and some of the energy is scattered by fish, pilings, seaweed, bubbles, etc. (*diffraction*). In addition, both the surface and bottom may affect the sound intensity by reflecting sound back into the water. The sound reflected by the surface and bottom may raise the intensity above normal levels (*reinforcement*) or may introduce *destructive interference*. The bending of the sound waves by temperature variations also has a great effect on the sound intensity at points remote from the source.

If the source of the sound is near the surface, there is some point beyond which sound is not received from the source. This point is said to be in a *shadow zone*. The distance from the source to the shadow zone is determined by the rate of change of temperature with depth, the depth of the source, and the depth at which the reception is made (Figure 6).

6.2.2 Water Density: In addition to these factors, water density is also important. Because the density of sea water varies with the temperature, the salt content, and the static pressure, the effect on sound of each of these three factors is usually considered separately.

6.2.3 Water Temperature: Variations in water temperature affect sound

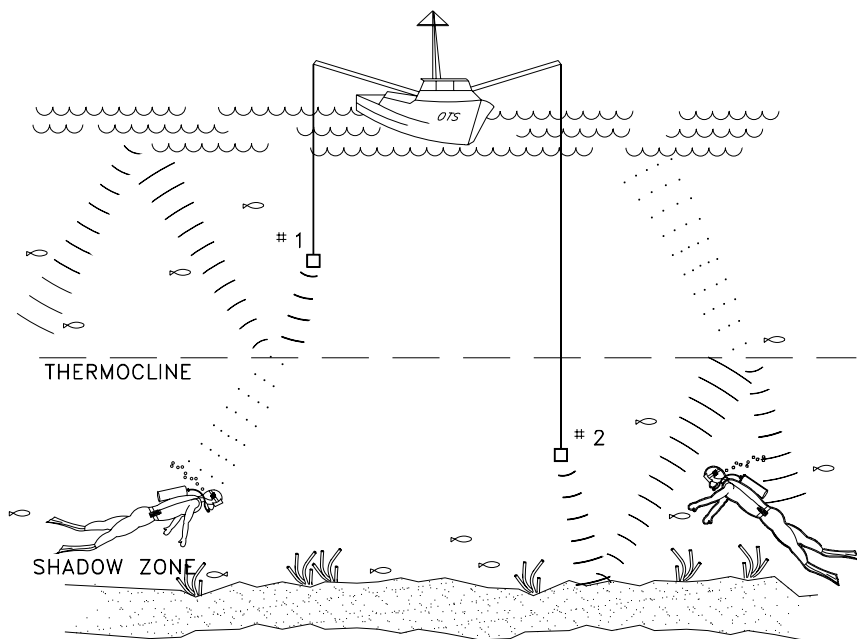


Figure 6: Thermoclines affect the ultrasonic signal. Divers must report thermocline depth(s) so the surface transceiver and/or other divers can be as close to the same depth as possible.

transmission most. In some areas of the ocean, the temperature changes at a fixed rate over large ranges of depth. If the temperature increases with depth at a fixed rate, the velocity of sound increases at a rate constant with depth and sound waves are refracted toward the surface. If, however, the temperature *decreases* with the depth (as is frequently the case), the velocity of sound decreases with depth and the waves of sound are bent downward.

There are also areas in the sea where, at some depth, temperature changes rapidly over a small depth range. Such a layer is referred to as a *thermocline* or *thermal layer*: Such layers, in addition to producing rather sharp bending of the sound waves by refraction effects, can serve as reflecting surfaces.

The velocity of sound transmission changes only about one percent for a temperature change of 10°F. However, the resultant bending of the sound path has great effect over a distance of several hundred yards.

If the temperature of the water decreases with depth at the rate of 1°F for each 30 feet (starting at the surface), most of the sound energy originating at the source near the surface will travel along paths that are bent rather sharply downward. Therefore, the sound energy may not reach a shallow detector positioned 1000 yards from the

source but may reach a deeper detector position further from the source. Greater temperature variations can cause these paths to bend more sharply.

The best method to deal with thermoclines is to bring the divers and/or transducers as close to each other as possible. If a diver enters a thermocline, he should report it to everyone (surface and divers) so they know the depth of the thermocline. All divers should stay within that depth, and the surface station should try to position the surface transducer below or above, whichever is the case (Figure 6).

6.2.4 Background Noise: Marine organisms play an important role in underwater acoustics. They are important primarily because of the effect they have on sound transmission, but they often serve as sources of underwater noise as well. High background noise—whether man-made, animal, or environmental (waves or rain)—can interfere with good communications. Such background noise can be suppressed through the use of the squelch function and thermoclines.

6.2.5 Zones of Silence: Large natural or man-made objects can block acoustical transmission under certain conditions, in much the same way that a rock blocks a fast-moving current of water. Close to the backside of the rock, in this example, the current is absent and the water seems still. A short distance away, the current is flowing again (Figure 7).

Similarly, acoustic energy in the water can be blocked if the transmitting source is

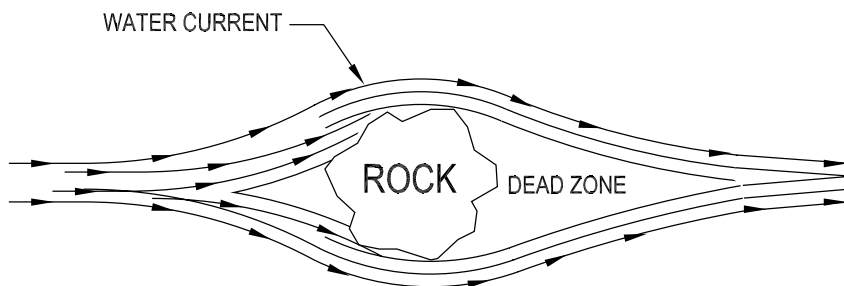


Figure 7. Water current dead zone

close to a large object. On the backside of the blocking object, a “zone of silence” is formed in which reception of the transmitted signal is not possible. Divers can reduce “zones of silence” by moving away from, around, or above the blocking object until communication is reestablished (Figure 8).

Most single sideband signals are efficient enough to permit communications around blocking objects. Reception is made mainly through surface and bottom reflections. Man-made noise may be present underwater in busy harbors, shipping lanes, and many coastal locations, particularly at lower frequencies. The outstanding characteristic of this coastal ambient noise is its great variability from place to place in the same harbor and from time to time at the same place.

Under some conditions, when your diving suit is directly between the transmitting source and your Aquacom® transceiver, a small zone of silence may be created that prevents reception. This effect becomes greater at longer ranges. Turning approximately 45 degrees in any direction eliminates this zone of silence.

Since most divers are in constant motion, it is unlikely that anything more than a momentary signal loss would occur when acoustic energy is blocked by air inside a dry suit, by gas bubbles within neoprene wet suit material, or when both are present—such as with a partially inflated dry suit.

- NOTE -

Now that you have read this operator's manual and have become familiar with the system, you are ready for your first communications dive with the Aquacom® SSB-2001B-2. If you apply what you've learned—especially the proper positioning of the earphone and transducer and slow, deliberate, relaxed speech—you can look forward to a new dimension in underwater experience.

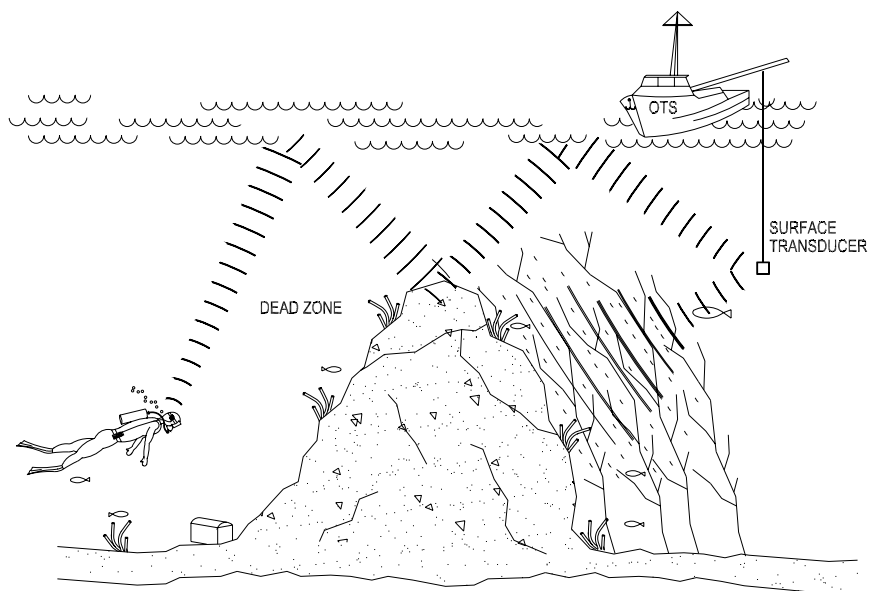


Figure 8. Communication through indirect and direct paths. Note kelp scattering sound. Without surface and bottom bounce, the diver would lose communications.

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LIMITED WARRANTY

Ocean Technology Systems' Aquacom[®] SSB-2001B-2 is fully warranted against defects in materials and workmanship for a period of 1 year from the time of purchase. Our obligation under this warranty is limited to the replacement of any part or parts which prove to our satisfaction to have been defective, and which have not been misused or carelessly handled. Labor is warranted for 1 year from time of purchase. The complete unit and/or part must be returned to our factory, transportation charges pre-paid. We reserve the right to decline responsibility where repairs have been made or attempted by other than an Ocean Technology Systems factory-trained service center or properly trained personnel. In no event shall Ocean Technology Systems be liable for consequential damages.

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Ocean Technology Systems

3133 W. Harvard Street, Santa Ana, CA 92704 USA

Telephone (714) 754-7848 • Toll-Free (800) 550-1984 • Fax (714) 966-1639

ots@otscomm.com • www.otscomm.com

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